

(1)

- FIRST PART : On the local structure of incompressible homogeneous and isotropic turbulence:

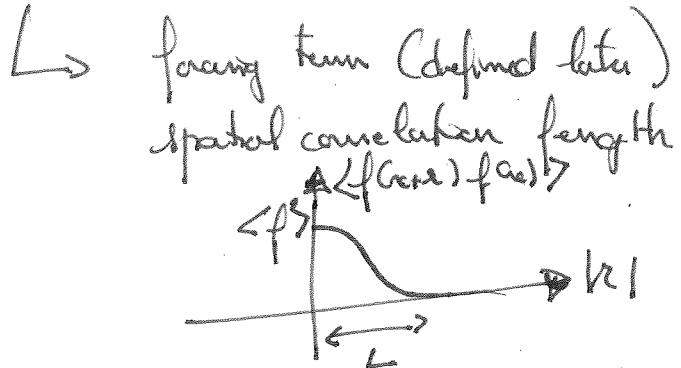
Balance of kinetic energy, axiomatics of Kolmogorov's phenomenology, and some illustrations.

- Very particular case of fluid turbulence
 - ↳ schematic
 - ↳ typically approach adopted in physics and mathematics

- Call L the "large scale"

in experiments, numerics,

size of the mesh
grid used in
"wind tunnels"
and/or diameter
of the nozzle of a
jet



- Scale L is typical of the scale at which energy is injected into the fluid.
- Non UNIVERSAL (depends in particular on the shape of the container)
- we will be mostly interested here in the behavior of velocity fluctuations at scales $l \ll L$.

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- The phenomenology that will be depicted is mostly based (and developed for) on experimental observations, in wind tunnels, under the Taylor approximation, with hot-wires.
(See for instance TOWNES AND LURKEY)

- Notations : Take $u(x, t) \in \mathbb{R}^3$ the (vector) velocity field.
- and consider the Navier-Stokes equations, $\tau(x, t) \in \mathbb{R}^3$

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} + (u \cdot \nabla) u = -\nabla p + \nu \Delta u + f \\ \operatorname{div} u = 0 \end{array} \right. \quad \begin{array}{l} \xrightarrow{\text{in } \mathbb{R}^3} \\ \text{discrete free forcing field.} \end{array}$$

or component by components

$$\left\{ \begin{array}{l} \frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \nu \Delta u_i + f_i \\ \operatorname{div} u = 0 \end{array} \right. \quad$$

Experiments, under

- Remark 1 : The Taylor's hypothesis, gives access to the streamwise velocity component (along the mean flow) say, for instance, $u_2(x_2, y_0, z_0, t_0)$ for a given set (y_0, z_0, t_0) and $u \in \mathbb{R}^3$.
- Remark 2 : NS equation is a closed set of non linear partial coupled equations.

In particular, pressure p is a given non local functional of the spatial distribution of velocity gradients, solution of the Poisson equation, and has nothing to do with the interpretation of pressure in a perfect gas.

• Similarity in fluid mechanics.

As we will see, the system NS ④ will eventually reach a statistically stationary state, in which variance of velocity fluctuations is finite.

Note $\boxed{\overline{u^2} = \langle |u|^2 \rangle}$

rem: for statistically homogeneous and isotropic flows.

$$\langle u_i u_i \rangle = 0 \text{ and } \overline{u^2} = \langle u_i u_j u_k \rangle = 3 \langle u_i^2 \rangle$$

ensemble.

→ Note $\overline{T} = \frac{L}{\overline{u}}$ the implied time scale
(called turnover time)

In the set of non-dimensionalized variables $(x', t') = (\frac{x}{L}; \frac{t}{T})$

define $u'(x', t') = \frac{1}{T} u(\frac{x}{L}; \frac{t}{T})$

$$p'(x', t') = \frac{T}{xL} p(\frac{x}{L}; \frac{t}{T})$$

$$f'(x', t') = \frac{T}{xL} f(\frac{x}{L}; \frac{t}{T})$$

N.S. reads

$$\boxed{\frac{\partial u'}{\partial t'} + (u' \cdot \nabla_{x'}) u' = - \nabla_x p' + \frac{1}{Re} \Delta_{x'} u' + f'}$$

where $Re = \frac{UL}{V}$ Reynolds number.

rem 1: only an illustration of the observation that in 3d hi.t., fluids of different viscosities have similar statistical behaviors at small scales for a given Reynolds number.

rem 2: In the following, I will use in a equivalent manner

$$\boxed{\begin{array}{l} Re \rightarrow \infty \\ \text{or} \\ V \rightarrow 0 \end{array}}$$

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• Kinetic Energy Budget.

Consider the (local) kinetic energy $e_k = \frac{1}{2} \text{let}^2$

Take use of N.S. equations to obtain:

$$\frac{1}{2} \frac{\partial \text{let}^2}{\partial t} + \operatorname{div} \mathbf{I} = -\nu \sum_{i,j=1}^3 \left(\frac{\partial u_i}{\partial x_j} \right)^2 + \text{uof}$$

- It is called a conservation equation

- \mathbf{I} : (spatial) vector current

$$\mathbf{I} = \frac{1}{2} \text{let}^2 \mathbf{u} + \rho \mathbf{u} \cdot \nabla \left(\frac{1}{2} \text{let}^2 \right)$$

$$- \nu \sum_{i,j=1}^3 \left(\frac{\partial u_i}{\partial x_j} \right)^2 \leq 0 \quad \text{viscous dissipation}$$

- uof : injected energy (power).

- Hints of the proof: take the scalar product of \mathbf{u} w.r.t N.S.

• remark \rightarrow Using incompressibility, pressure contributions are of divergence-type: $\mathbf{u} \cdot \nabla p = \nabla \cdot (\rho \mathbf{u})$

\rightarrow Using incompressibility, nonlinear contributions are of divergence-type: $\mathbf{u} \cdot [\mathbf{u} \cdot \nabla p] = \nabla \cdot \left(\frac{1}{2} \text{let}^2 \rho \mathbf{u} \right)$

\rightarrow Again with incomp.

$$\mathbf{u} \cdot \Delta \mathbf{u} = \operatorname{div} \nabla \left(\frac{1}{2} \text{let}^2 \right) - \sum_{i,j=1}^3 \left(\frac{\partial u_i}{\partial x_j} \right)^2$$

- Consequences on global and averaged kinetic energy.

Courchesne $E_c(t) = \int_{x \in V} \frac{1}{2} |u|^2(x, t) d^3x$

→ Thus $\frac{\partial E_c}{\partial t}$ governed by competition of (global) viscous dissipation and (global) expected power + flux of I through the boundaries.

divergence theorem ↑

- In a statistically homogeneous (and isotropic) flow, the average current $\langle I(x) \rangle$ independent on x , therefore $\langle \operatorname{div} I \rangle = \operatorname{div} \langle I \rangle = 0$

therefore $\frac{\partial \langle E_c \rangle_{st}}{\partial t} = - \underbrace{\left\langle \nu \sum_{i,j=1}^3 (\partial u_i / \partial x_j)^2 \right\rangle}_{-\varepsilon} + \langle f \cdot u \rangle$

- (As observed) $\frac{\partial \langle E_c \rangle}{\partial t} = 0$: statistically stationarity.
 $\langle E_c \rangle = \frac{1}{2} \bar{\varepsilon} = \frac{3}{2} \langle e_k^2 \rangle$

↳ Axiomatics of Kolmogorov gives a consistent phenomenology of the kinetic energy budget at infinite Reynolds number, or equivalently, when $\nu \rightarrow 0$.

Axiomatics of Kolmogorov, and the phenomenology of
 (3d) fully developed turbulence.

- ① When stirred at large scales, the velocity field reaches a statistically stationary regime such that

$$\lim_{R \rightarrow \infty} \lim_{t \rightarrow \infty} \left\langle \frac{2}{3} u_1^2(t) \right\rangle = \bar{S}^2 < +\infty$$

rem : Far from being obvious from the dynamics.
 → see illustration with the stochastic heat equation.

- The limit $\omega \rightarrow 0$ can be tested experimentally (using for instance Helium gas close to the critical point ; see work of Cercignani et al.)

- ② To ensure such an efficient way to dampen energy, (maintaining in particular finite kinetic energy), the flow will develop small scales (non provided by the forcing) such that

$$\lim_{v \rightarrow 0} \lim_{t \rightarrow \infty} E(t) \left\langle \left(\sum_{i,j=1}^3 \partial_{ij} u_i \right)^2 \right\rangle = \varepsilon > 0$$

- Incidentally velocity gradient variance diverges like $\frac{1}{r}$
- Incidentally, ε is governed by the flow at large scales, no other choices than $\boxed{\varepsilon = O(\frac{R^3}{L})}$

- Incidentally, $\varepsilon = \langle f \cdot u \rangle$
 Even at infinite Reynolds number, the flow "follows" the forcing, and keeps a finite correlation with it.

→ Experimental observations:

In a statistical homogeneous and isotropic framework, the two-point structure of turbulence is fully characterized by the correlation function of the streamwise component

$$[f(h) \cdot f(h)] = \langle u_s(x_1, y, z, t) u_s(x_1 + h, y, z, t) \rangle$$

- In particular:

$$\boxed{C_{ij}(h) = \langle u_i(x) u_j(h) \rangle = \frac{f(|h|) - g(|h|)}{|h|^2} (h_i h_j + g(|h|) \delta_{ij})}$$

where $g(|h|) = f(|h|) + \frac{1}{2} |h| f'(|h|)$

"transverse" correlation function

- Incidentally, the correlation of velocity gradients is determined by the variance of the gradient of the streamwise component,

$$f''(0) = -\langle (\partial_{x_1} u_2)^2 \rangle.$$

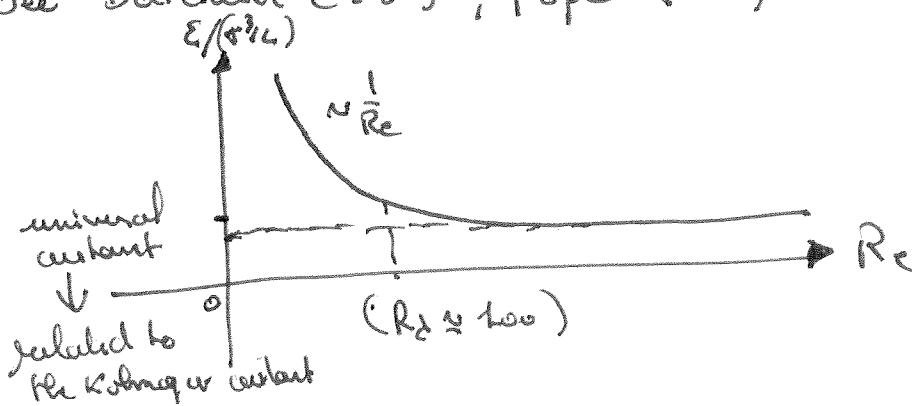
Noting use of $\langle \frac{\partial u_i(x)}{\partial x_k} \frac{\partial u_j(x)}{\partial x_p} \rangle = - \left. \frac{\partial^2}{\partial x_k \partial x_p} C_{ij}(h) \right|_{h=0}$

we get

$$\langle \frac{\partial u_i(x)}{\partial x_k} \frac{\partial u_j(x)}{\partial x_p} \rangle = 2 \langle (\partial_{x_1} u_2)^2 \rangle [\delta_{ij} S_{kp} - \frac{1}{4} \delta_{ik} \delta_{jp} - \frac{1}{4} \delta_{ip} \delta_{jk}]$$

such that $E = \nu \langle (\partial_{x_1} u_2)^2 \rangle = 15 \nu \langle (\partial_{x_1} u_2)^2 \rangle$

See Batchelor (53), Pope (80)



See compilation of data by Sreenivasan, Konda et al.

③ Concerning the existence of velocity differences at infinite Reynolds number

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- Velocity gradients are infinite
- (kinetic energy budget makes sense only in a distributional sense)
- fluid velocity is rough, but bounded and continuous.
"weak"
- Consider the (longitudinal) velocity increment

$$\langle \delta u_{\text{ext}}(x) \rangle = u_0(x_0) - u_0(x)$$

- $l/3$ -law : Reach the statistically stationary regime, and observe that in good approximation, Hart.

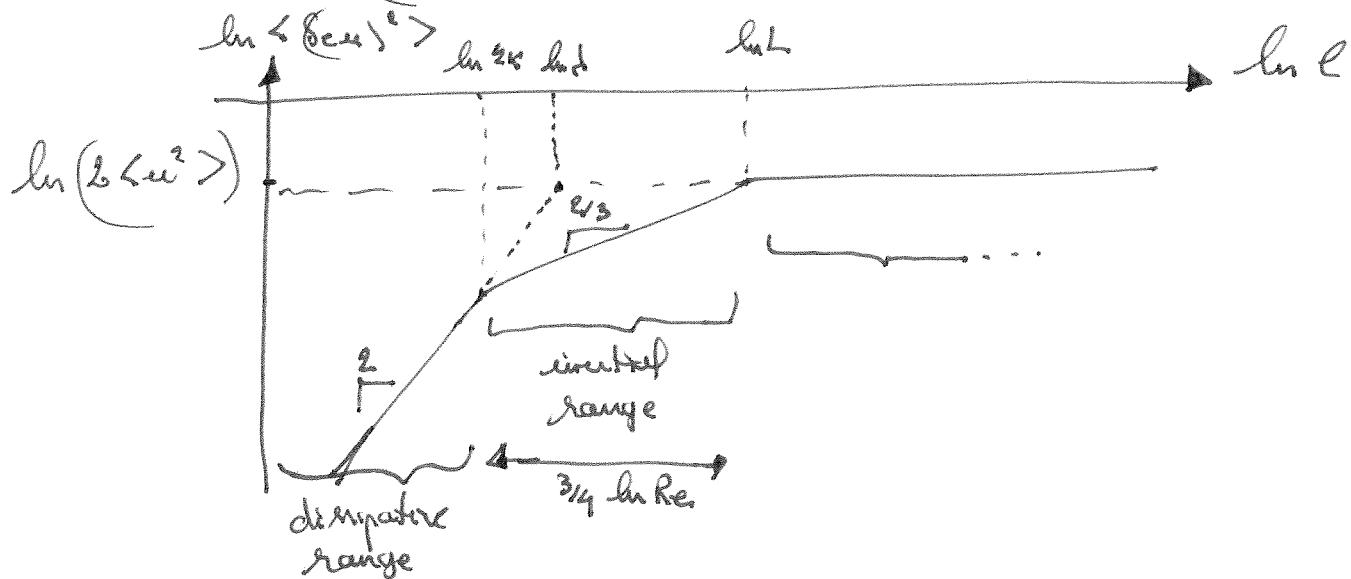
$$\lim_{v \rightarrow 0} \left\langle (\delta u_e)^2 \right\rangle \underset{l \rightarrow 0}{\not\propto} C_2(\epsilon e)^{\frac{2}{3}}$$

with $C_2 \approx 1$, except on large scale geometries and low Reynolds numbers.

- At a finite Re , this implies a new lengthscale η_K defined as the typical scale at which velocity loses regularity:

$$\left\langle (\delta u_e)^2 \right\rangle \approx \begin{cases} C_2(\epsilon e)^{\frac{2}{3}} & l \gtrsim \eta_K \\ l^2 \left\langle (\partial u_e)^2 \right\rangle & l \lesssim \eta_K \end{cases}$$

$$\Rightarrow \eta_K \sim \left(\frac{v^3}{\epsilon} \right)^{\frac{1}{4}} \sim L Re^{-\frac{3}{4}}$$



Ans: Pictures may too schematic to obtain the correct interpretation
of behavior (boundary terms will dominate in the
interesting range of scales) (2)

Nonetheless, keep in mind that this corresponds to

$$E(Q) = \int_0^{\infty} \cos(\ell Q) \left[1 - \frac{(\sec)^2}{\ell^2} \right] d\ell$$

$$\sim_{\ell \rightarrow \infty} (\text{cte}) \ell^{-5/3}$$

↪ ask BOS
Lohse - Müller Goedert 95

• First illustration of the standard phenomenology of turbulence.

↳ Studying solution of the stochastic heat equation.

Consider in dimension d the (randomly) forced heat equation

$$\frac{\partial u}{\partial t} = \nu \Delta u + f(x,t)$$

where $f(x,t)$ is a Gaussian field, delta correlated in time,
delta correlated in space:

$$\text{for instance : } \langle f(x,t_1) f(y,t_2) \rangle = A e^{-\frac{|x-y|^2}{2L^2}} \delta(t_1-t_2)$$

Using fundamental solution of H.E. (Green function), starting from $u(x,0) = 0$, we get

$$u(x,t) = \int_0^t \int_{\mathbb{R}^d} \frac{1}{4\pi\nu(t-s)} e^{-\frac{|x-y|^2}{4\nu(t-s)}} f(y,s) dy ds$$

→ Consequences on velocity variance :

$$\text{by homogeneity } \rightarrow \langle u^2(t) \rangle = \int_0^t ds \left[\frac{1}{4\pi\nu(t-s)} \right]^d \int_{\mathbb{R}^d \times \mathbb{R}^d} e^{-\frac{|y|^2+|z|^2}{4\nu(t-s)}} e^d dy dz$$

$$\text{Gaussian integrals : } \int_{\mathbb{R}^d \times \mathbb{R}^d} e^{-\frac{|y|^2+|z|^2}{4\nu(t-s)}} e^{-\frac{|y-z|^2}{2L^2}} dy dz$$

$$= \left[\int_{\mathbb{R}^{2d}} e^{-\frac{|y|^2+|z|^2}{4\nu(t-s)} - \frac{(y-z)^2}{2L^2}} dy dz \right]^d = \left[4\pi\nu(t-s) \sqrt{\frac{L^2}{2L^2 + 8\pi\nu(t-s)}} \right]^d$$

such that

$$\begin{aligned} \langle u^2(t) \rangle &= \int_0^t ds \left[\frac{L^2}{2L^2 + 8\pi v(t-s)} \right]^{d/2} \\ &= \int_0^t ds \left[\frac{1}{1 + \frac{8\pi v(t-s)}{2L^2}} \right]^{d/2} \quad t = \frac{8\pi v(t-s)}{2L^2} \\ &= \frac{L^2}{4\pi v} \times \int_0^{\frac{4\pi v t}{L^2}} \frac{1}{1 + x^2} dx \end{aligned}$$

so :

- $d=1 \Rightarrow \langle u^2(t) \rangle \xrightarrow[t \rightarrow \infty]{} \infty \text{ as } \sqrt{t}$
- $d=2 \Rightarrow \langle u^2(t) \rangle \xrightarrow[\infty]{} \infty \text{ as } \ln t$
- $d>3 \Rightarrow \langle u^2(t) \rangle \xrightarrow[\infty]{} \frac{L^4}{4\pi v} \frac{1}{d-2}$

In all cases, the stochastic heat equation (diffusion) is not efficient enough to dampen the expected energy.

- or it does not reach a stationary regime ($d \leq 2$)
- or variance behaves as $t^{1/d}$ ($d > 3$)

→ Consequences on viscous dissipation:

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Similarly,

$$\langle \partial_i u_i(t) \rangle = - \int_0^t \int_{\mathbb{R}^d} \frac{1}{(4\pi\nu(t-s))^{d/2}} \frac{x_i - y_i}{8\nu(t-s)} e^{-\frac{|y_i|^2}{4\nu(t-s)}} f(y, s) dy ds$$

such that (by homogeneity)

$$\langle |\nabla u|^2 \rangle = \int_0^t \left[\frac{ds}{4\pi\nu(t-s)} \right]^d \int_{\mathbb{R}^d \times \mathbb{R}^d} \frac{y \cdot z}{[8\nu(t-s)]^2} e^{-\frac{|y|^2 + |z|^2}{4\nu(t-s)}} - \frac{|y-z|^2}{2L^2} dy dz$$

$$\begin{aligned} & \xrightarrow{\text{isotropy}} \\ &= d \int_0^t \left[\frac{ds}{4\pi\nu(t-s)} \right]^d \int_{\mathbb{R}^d \times \mathbb{R}^d} \frac{yz}{[8\nu(t-s)]^2} e^{-\frac{|y|^2 + |z|^2}{4\nu(t-s)} - \frac{|y-z|^2}{2L^2}} dy dz \\ &= d \int_0^t \left[\frac{ds}{4\pi\nu(t-s)} \right]^d \left[\int_{\mathbb{R}^d \times \mathbb{R}^d} \frac{yz}{[8\nu(t-s)]^2} e^{-\frac{|y|^2 + |z|^2}{4\nu(t-s)} - \frac{|y-z|^2}{2L^2}} dy dz \right] \\ & \quad \left[\int_{\mathbb{R}^d \times \mathbb{R}^d} e^{-\frac{|y|^2 + |z|^2}{4\nu(t-s)} - \frac{|y-z|^2}{2L^2}} dy dz \right]^{d-1} \end{aligned}$$

$$\begin{aligned} & \xrightarrow{2} \frac{d}{2L^2} \int_0^t \frac{1}{[1 + 8\pi\nu \frac{t-s}{L^2}]^{d/2}} ds = \frac{d}{2L^2} \frac{L^2}{4\pi\nu} \int_0^{\frac{4\pi\nu t}{L^2}} \frac{1}{[1+t]^{d/2}} dt \\ &= \frac{d}{8\pi\nu} \int_0^{\frac{4\pi\nu t}{L^2}} \frac{1}{(1+t)^{d/2}} dt \end{aligned}$$

- $d=1 \Rightarrow \langle |\nabla u|^2 \rangle \xrightarrow{\infty} \infty \text{ as } \ln t$

- $d>2 \Rightarrow \boxed{\nu \langle |\nabla u|^2 \rangle \xrightarrow{\infty} \frac{1}{4\pi} \frac{d}{d-1}}$

ϵ is finite, independently on viscosity!
(but variance diverges)

• Second illustration: Fractional Gaussian field.

Can we give a (probabilistic) meaning to the velocity field depicted in the phenomenology of Kolmogorov?

• a random field such that

① Variance is finite (when $\nu \rightarrow 0$)

② Velocity derivative finite (when $\nu \rightarrow 0$)

③ Hölder continuity $\lim_{\nu \rightarrow 0} \left(u(x_\ell) - u(x_0) \right)^2 \sim \ell^{2/3}$
 x_0 ?

• Stay simple (i.e. theoretical), adopt a Gaussian approximation

• Consider

$$\mu_y(x) = \int_{\mathbb{R}^d} f_x(x-y) |x-y|^{-\frac{H-d}{2}} w(dy)$$

• $w(dy)$: "White Gaussian noise"

(on a discrete set, made up of independent Gaussian random variable, zero average, variance $(dx)^d$)

obeying the following rule of calculation:

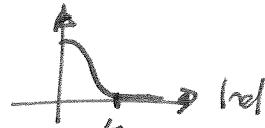
$$\left\{ \begin{aligned} E[\int f(y) w(dy)] &= 0 \\ E[\int f(y) w(dy) \int g(y) w(dy)] &= \int_{\mathbb{R}^d} f(y) g(y) dy \end{aligned} \right.$$

$$\left. \begin{aligned} E[\int f(y) w(dy)] &= 0 \\ E[\int f(y) w(dy) \int g(y) w(dy)] &= \int_{\mathbb{R}^d} f(y) g(y) dy \end{aligned} \right.$$

• A "regularized" norm $|x|_y = \begin{cases} |x| & \text{for } |x| \geq y \\ y & \text{for } |x| \leq y \end{cases}$

over a "small" length scale y (that will eventually depend on ν)

• f_x a large scale cut-off, non universal



As mentioned, the field is regularized over $\chi(v)$,
s.t. it is differentiable.
what happens when $\chi(v) \rightarrow 0$?

Consider the variance. (by homogeneity)

$$\langle u_\chi^2(\omega) \rangle = \int_{\mathbb{R}^d} \mathcal{L}_L^2(y) |y|^\chi \frac{dy}{\chi} \stackrel{\chi \rightarrow 0}{\longrightarrow}$$

\hookrightarrow for the sake of presentation, consider $d=1$

$$\Rightarrow \langle u_\chi^2(\omega) \rangle = \int_{\mathbb{R}} \mathcal{L}_L^2(y) |y|^\chi dy \stackrel{\chi \rightarrow 0}{\longrightarrow}$$

the limit exists iff the singularity at the origin is integrable, which is the case for $H > 0$

$$\Rightarrow \langle u_\chi^2(\omega) \rangle \underset{\chi \rightarrow 0}{\longrightarrow} \int_{\mathbb{R}} \mathcal{L}_L^2(y) |y|^{H-1} dy < \infty$$

It is finite and non singular:

Now, consider first $w \rightarrow 0$ (variance remains bounded),
and consider the increment of the field

$$\Delta u(\omega) = u(\omega + \ell) - u(\omega)$$

$$\langle \Delta u^2(\omega) \rangle = \int_{\mathbb{R}} \Phi_e^2(y) dy$$

$$\Phi_e(y) = \mathcal{L}_L(\ell-y) |y|^{H-\frac{1}{2}} - \mathcal{L}_L(y) |y|^{H-\frac{1}{2}}$$

Now, the question is : How behaves this asymptotic velocity field when $l \rightarrow 0^+$?

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$$\langle S_{\text{err}}^2 \rangle = l \int_{\mathbb{R}}^{2H} \left[f_L(l(1-y)) |l-y|^{H-\frac{1}{2}} - f_L(ly) |y|^{H-\frac{1}{2}} \right]^2 dy$$

$$\underset{l \rightarrow 0}{\sim} f_L(0) l^{2H} \int \left[|l-y|^{H-\frac{1}{2}} - |y|^{H-\frac{1}{2}} \right]^2 dy$$

→ true if the integral is finite.
We only have to check integrability at infinity.

Remark that $|l-y|^{H-\frac{1}{2}} - |y|^{H-\frac{1}{2}} \underset{y \rightarrow \infty}{\sim} y^{H-\frac{1}{2}} \left[\left(1 - \frac{1}{y}\right)^{H-\frac{1}{2}} - 1 \right]$

$$y^{H-\frac{1}{2}} \left[-\frac{1}{4} \left(H-\frac{1}{2}\right) \right]$$

$$\underset{y \rightarrow \infty}{\sim} \left(H-\frac{1}{2}\right) y^{H-\frac{3}{2}}$$

→ The integrand behaves $\left(H-\frac{1}{2}\right) y^{2H-3}$ for $y \rightarrow +\infty$
→ integral is finite iff $\boxed{H < 1}$

- Conclusions, for $0 < H < 1$, the field is asymptotically of finite variance (depends on the cut-off), and the structure function behaves as

$$\lim_{l \rightarrow 0} \langle S_{\text{err}}^2 \rangle \underset{l \rightarrow 0}{\sim} f_L(0) l^{2H} \int \left[|l-y|^{H-\frac{1}{2}} - |y|^{H-\frac{1}{2}} \right]^2 dy$$

So the field is not differentiable, and univocal
(depends only on $f_L(0)$) !

- Further calculations shows that

$$\langle |\nabla u_\eta|^2 \rangle \underset{\eta \rightarrow 0}{\sim} \gamma^{2H-2} \text{cte}(H, d)$$

(it is indeed non differentiable)

- Thus, it is enough to take

$$y(v) = v^{-\frac{1}{2H-2}} = v^{\frac{1}{2-2H}} \xrightarrow[v \rightarrow 0]{} 0$$

to ensure that

$$v \langle |\nabla u_{\eta(v)}|^2 \rangle \xrightarrow[v \rightarrow 0]{} \text{cte.}$$

- In particular, $\boxed{H = \frac{1}{3}}$

$$\text{we have } \langle (\delta u)^2 \rangle \sim l^{4/3}$$

$$\text{and } \nu(\tfrac{1}{3}) = v^{3/4} \not\propto \mathcal{M}_K$$

Second part: Energy transfer through scales, and Intermittency.

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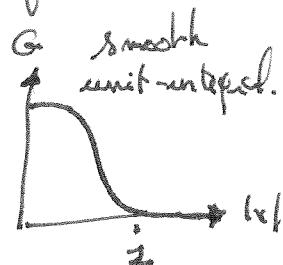
- Former kinetic energy budget evaluated the role played by viscous dissipation. Further interpretation leads us to expect non-differentiable velocity fields at infinite Reynolds numbers.

- Counter
- Budget exhibits anomalies (i.e. distributional) quantities
- It is thus tempting to study the energy budget of a coarse-grained version of velocity, such as:

$$u^l(x,t) = \int G_l(y) u(y,t) dy \xrightarrow[l \rightarrow 0]{\text{pointwise}} u(x,t)$$

where G_l is an isotropic mollifier = approximation of the Dirac S-function at scale l :

$$G_l(x) = G_l(lx) = \frac{1}{l}, \quad G\left(\frac{|x|}{l}\right)$$



- Kinetic budget exhibits a new term
(see literature on Large Eddy Simulations)
involving the turbulent stress $\tau_{ij}(x) = (u_i u_j)(x) - \bar{u}_i \bar{u}_j \delta^{ij}(x)$

- Instead, consider that

$$|u^l(x,t)|^2 = \int G_l(x-y) G_l(x-z) \underbrace{u(y,t) \cdot u(z,t)}_{\text{two-points}} dy dz$$

- Budget of the point-split kinetic energy: ?
- $$\epsilon_{xx}^{ll}(x) = \frac{1}{l} u(x,t) \cdot u(x+l,t)$$

- Here, we follow Greg Eyring's derivation
(his notes on turbulence theory are a must).

Define : $u = u(x, t)$, $p = p(x, t)$

$$u' = u(x, t) ; \quad p' = p(x, t)$$

$$\delta u = u' - u = u(x, t) - u(x, t)$$

From N.S., we get:

$$\boxed{\frac{1}{2} \frac{\partial(u \cdot u')}{\partial t} + \operatorname{div} J = -\nu \sum_{i,j=1}^3 \partial_j u_i \partial_j u'_i + \frac{1}{2} (u \cdot f + u' \cdot f) + \frac{1}{4} \nabla p \cdot [\operatorname{div} |\delta u|^2]}$$

- Similar interpretations as the former budget, but action of a new term.

$$J = \left(\frac{1}{2} u \cdot u' \right) u + \frac{1}{2} (p u' + p' u) + \frac{1}{4} \nabla p \cdot \delta u - \nu \operatorname{grad} \left(\frac{1}{2} u \cdot u' \right)$$

Hints on the proof:

- The viscous contribution is written as

$$u \cdot \Delta u' + u' \cdot \Delta u = \operatorname{div} [\operatorname{grad}(u \cdot u')] - 2 \sum_{i,j=1}^3 \partial_j u_i \partial_j u'_i$$

- Similarly, pressure only participates in redistribution of energy in space.

• Crucial contribution of the non linear term :
 (again, take a look at the notes of Greg Eyring) (19)

$$\begin{aligned}
 u \cdot [(\bar{u} \cdot \nabla) \bar{u}'] + \bar{u} \cdot [\bar{u} \cdot \nabla] u &= \bar{u}^i \partial_j (\bar{u}'^j \bar{u}_j) + \bar{u}'^i \partial_j (\bar{u}_i \bar{u}_j) \\
 &= \underbrace{\bar{u}^i \partial_j (\bar{u}'_i \bar{u}_j)}_{\text{div } [\bar{u} (\bar{u}' \bar{u})]} - \bar{u}_i \bar{u}_j \partial_j \bar{u}'^i + \underbrace{\partial_j (\bar{u}'_i \bar{u}_i \bar{u}_j)}_{\text{div } [\bar{u} (\bar{u}' \bar{u})]}
 \end{aligned}$$

$\Rightarrow \approx \bar{u}_i \bar{u}'^j \partial_j \bar{u}'^i - \bar{u}_i \bar{u}_j \partial_j \bar{u}'^i$
 $\approx \bar{u}^i \text{S}_{ij} \partial_j \bar{u}'^i \quad \textcircled{*}$

Remark That : ○ by incompatibility

$$\begin{aligned}
 \nabla_k \cdot [\bar{u} \bar{u} | \bar{u}|^2] &= [\cancel{\bar{u}} \bar{u}^i \cancel{\partial}_k \bar{u}_i + (\bar{u} \cdot \nabla_k) \bar{u} | \bar{u}|^2] \\
 &= \bar{u} \bar{u}^j \partial_j \bar{u}_i \bar{u}_i = 2 \bar{u} \bar{u}^j \partial_j \bar{u}_i \bar{u}_i \\
 &= 2 \bar{u}_i \bar{u}^j \partial_j \bar{u}'^i \\
 &= 2 \bar{u}'^i \bar{u}^j \partial_j \bar{u}'^i - 2 \bar{u}_i \bar{u}^j \partial_j \bar{u}'^i \\
 &= \bar{u} \bar{u}^j (\partial_j |\bar{u}'|^2) - 2 \textcircled{*} \\
 &= \text{div } [|\bar{u}'|^2 \bar{u}] - 2 \text{ (nonlinear contribution)}
 \end{aligned}$$

- This local budget of the point-pair energy allows to discuss the local conservation, or non-conservation, of kinetic energy in a more general framework:

- without assuming differentiability
(but assuming Hölder-continuity)
(with appropriate functional spaces)
- gives a proof of Onsager's conjecture

See devoted works of {
 Constantin - E- Titi
 Danchon - Robert

and more recent ones of Bechmeister, De Lellis,
 Idet, Székelyhidi, etc...

→ ask Dubrulle.

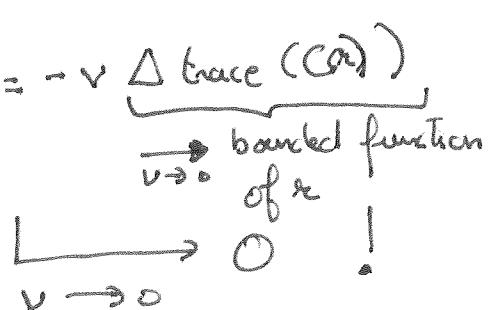
- Adopt a simpler statistical approach, and assume statistical stationarity, homogeneity, isotropy -

We get:

$$\frac{1}{4} \nabla_x \cdot \langle \mathbf{u} | \mathbf{u} |^2 \rangle - v \sum_{i,j=1}^3 \langle \partial_{j,i} u_i \partial_{j,i} u_i \rangle + \frac{1}{2} \langle \mathbf{u} \cdot \mathbf{f}' + \mathbf{u}' \cdot \mathbf{f} \rangle = 0$$

- Viscous contribution $v \sum_{i,j=1}^3 \langle \partial_{j,i} u_i \partial_{j,i} u_i \rangle = -v \underbrace{\Delta \text{trace}(\mathbf{C}\mathbf{u})}_{\begin{array}{l} \xrightarrow{v \rightarrow 0} \text{banded function} \\ \text{of } \mathbf{u} \end{array}}$

where $C_{ij}(r) = \langle u_i(r) u_j(r) \rangle$



- forcing contribution: $\lim_{|r| \rightarrow 0} \lim_{v \rightarrow 0} \frac{1}{2} \langle \mathbf{u} \cdot \mathbf{f}' + \mathbf{u}' \cdot \mathbf{f} \rangle = \langle \mathbf{u} \cdot \mathbf{f} \rangle = E$

We are left with

$$\lim_{|x| \rightarrow 0} \lim_{\nu \rightarrow 0} \nabla \cdot \langle \delta u |\delta u|^2 \rangle = -4E$$

which says that $\langle \delta u |\delta u|^2 \rangle = -\frac{4}{3}E$
 (heuristically)
 when $\nu \rightarrow 0$ and then $|x| \rightarrow 0$

- Consequences for the coarse-grained energy: (Switch off forcing)

$$\underbrace{\frac{d\langle |u^e|^2 \rangle}{dt}}_{\text{evolution of kinetic}} = \int G_e(x-y) G_e(x-z) \frac{d}{dt} \langle u(y) \cdot u(z) \rangle dy dz$$

energy of "scales" $\geq l$

$$\xrightarrow{\nu \rightarrow 0} \int G_e(x-y) G_e(x-z) \frac{1}{4} \nabla p_{y-z} \langle \delta u |\delta u|^2 \rangle dy dz$$

$$\underset{l \ll L}{\approx} -E.$$

That says that kinetic energy "cascade" through scales at the rate E , independently of the scale.

• Experimental check and derivation of the 4/5-law

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Only the longitudinal velocity increment is accessible in wind tunnels
(along the mean flow)

→ Make use of statistical homogeneity and isotropy to relate
 $\langle S_{u_1} |\delta u_1|^2 \rangle$ to $\langle S_{u_1} |\delta u_{\parallel}|^2 \rangle$

$$\text{where } S_{u_{\parallel}}(r) = [u(r+r) - u(r)] \cdot \frac{r}{|r|}$$

For full derivation, see Frisch (95).

Hints of the proof:

• remark that

- by homogeneity
- will not contribute cause $\nabla u_j \rightarrow 0$

$$\begin{aligned} \langle S_{u_j} |\delta u_1|^2 \rangle &= \overbrace{\langle u_i' u_i' u_j' \rangle - \langle u_i u_i u_j' \rangle} + \overbrace{\langle u_i u_i u_j' \rangle - \langle u_i' u_i' u_j' \rangle} \\ &\quad + 2 \langle u_i u_i u_j' \rangle - 2 \langle u_i' u_i' u_j' \rangle \end{aligned}$$

→ require knowledge of $b_{ij,m}(r) = \langle u_i(r) u_j(r) u_m(r+r) \rangle$

► Batchelor, Monin - Obukhov, Frisch

$$b_{ij,m}(r) = C(h) S_{ij} \frac{r_m}{|r|} + D(h) \left[S_{im} \frac{r_j}{|r|} + S_{jm} \frac{r_i}{|r|} \right] + F(h) \frac{r_i r_j r_m}{|r|^3}$$

Incompressibility $\partial_m b_{ij,m}(r) = 0$ gives D and F as functions of C and its derivative

- Obtain $B_{ijm} = \langle \delta u_i \delta u_j \delta u_m \rangle$ from b_{ijm}

- Notice that $\langle (\delta_{ii} u)^3 \rangle = B_{ijm} \frac{\epsilon_{ijk} \epsilon_{ilm}}{|x|^3} = -18 C$

showing that $\langle \delta u_i \delta u_i^2 \rangle$ can be expressed only in terms of the longitudinal velocity increment.

- Go on with the calculation, and get

$$\boxed{\lim_{v \rightarrow 0} \left\langle \left[(\epsilon_{i(x+v)} - \epsilon_{ix}) \cdot \frac{x}{|x|} \right]^3 \right\rangle \underset{|x| \rightarrow 0}{\sim} -\frac{4}{5} \epsilon |x|}$$

- Experimental check \rightarrow Gagne et al. PoF (2004)

• Higher order statistics, Intermittency, and their stochastic modeling

We have seen that, at "small" scales (i.e. in the inertial range):

$$\bullet \langle (\delta e_{\text{in}})^2 \rangle \approx C_k(\epsilon e)^{2/3}$$

- We were able to draw a Gaussian representation using fractional Gaussian fields.

$$\Rightarrow \delta e_{\text{in}} \text{ "is" } \underbrace{\sqrt{\left(\frac{l}{L}\right)^3} \mathcal{N}(0, 1)}_{\text{Gaussian random variable}} \text{ o-average, unit variance}$$

as far as 1-point statistics of increments are concerned!

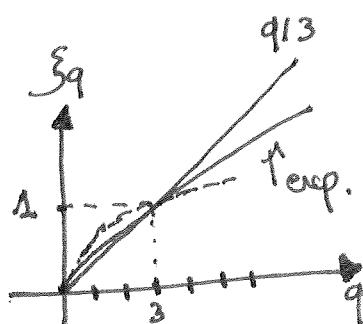
BUT $\langle (\delta e_{\text{in}})^3 \rangle = -\frac{4}{5} \epsilon e \neq 0$

- The Gaussian interpretation is not realistic
- Furthermore, the probability density functions (PDFs) of increments are strongly non-Gaussian
- See Frisch (95)

- In a (mostly) equivalent way:

$$\langle (\delta e_{\text{in}})^q \rangle = C_q(\epsilon e)^{\xi_q}$$

with ξ_q a nonlinear function of q



- Instead, a more realistic picture would be given by this equality in "law"

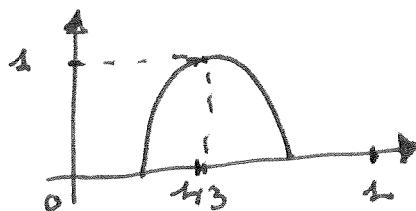
$$\text{S}_{\text{ell}} \text{ "law"} = \sigma \left(\frac{l}{L} \right)^h N(0, 1)$$

where h is no more unique, and fluctuates around $\frac{1}{3}$ according to a given universal (in a certain sense) probability density:

At a scale l , this density is given by

$$P_e(h) = \frac{1}{Z(l)} \left(\frac{l}{L} \right)^{1-D(h)}$$

$D(h)$: called the singularity spectrum, universal
(independent of scales, Reynolds number,
large scale anisotropies, etc.)



In essence, this is the multifractal formalism.
(see textbook of Frisch).

- If furthermore, h and the $N(0, 1)$ random variable are assumed independent, we can show that

$$\langle (\text{S}_{\text{ell}})^q \rangle = C q \left(\frac{l}{L} \right)^{\delta q}$$

with

$$\delta q = \min_h [qh + 1 - D(h)]$$

Former picture still too mathematical, since

$$c_q = \mathbb{E} \left[C_q \right] >$$

$$= 0 \quad \text{for } q \text{ odd.}$$

In particular $\boxed{C_3 = 0}$, not consistent with $4/5$ -law

- Vast literature on the precise choice for $\mathcal{P}(h)$ able to reproduce experimental data. ("lognormal", She-Lévéque etc.)

- From the theoretical side, it is very convenient to assume Gaussian statistics for h

- corresponding to

$$\mathcal{P}(h) = 1 - \frac{(h - c_1)^2}{2c_2}$$

$$\text{with } c_1 = \frac{1}{3} + \frac{3}{2}c_2$$

$$c_2 = 0.025 \quad (\text{obtained from Experiments - DNS})$$

- corresponding to

$$\boxed{\mathcal{E}q = c_1 q + c_2 \frac{q^2}{2}}$$

- $\mathcal{E}_3 = 1$

- $\mathcal{E}q$ realistic of data for $q \leq 6$

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- Beyond Fractional Gaussian fields: towards Multifractality

Main probabilistic tools borrowed from Yaglom, Mandelbrot, Kacene and many others over the last 60 years.

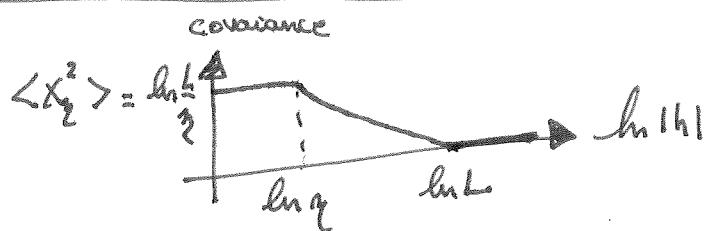
I follow here, mostly, some propositions made in a concise way by Robert and Vargas (CNP, 2008).

- Consider
$$M_\gamma(x) = \int_{\mathbb{R}} I_\gamma(y) |x-y|^{1-\frac{\gamma}{2}} e^{\gamma X_\gamma(y) - \frac{\gamma^2}{2} \langle X_\gamma^2 \rangle} W(dy)$$

- $X_\gamma(x)$ a zero-average Gaussian field, with appropriate (defined later) covariance structure
- γ : a free parameter, that will eventually play the role of the intermittency coefficient $c_2 = \gamma^2 = 0.25$.
- We assume X_γ and W independent.
- Item: Since X_γ is Gaussian, we have $\boxed{\langle e^{\gamma X_\gamma} \rangle = e^{\frac{\gamma^2}{2} \langle X_\gamma^2 \rangle}}$
- Item: For these conditions, the covariance of the velocity field $\langle M_\gamma(0) M_\gamma(x) \rangle$ is the same as the corresponding Fractional Gaussian Field (take $\gamma=0$)

- To reproduce the formerly depicted phenomenology of intermittency, we have to take for the covariance of X_η a logarithmic structure, of the form :

$$\langle X_\eta(a) X_\eta(b) \rangle = \ln \frac{L}{|b-a|^\eta} \quad 1_{|b-a| \leq L}$$



- In a good approximation, that warrants statistical homogeneity, X_η is given by a Fractional Gaussian field of vanishing H=0.

$$X_\eta(x) = \frac{1}{\sqrt{2}} \int_{\mathbb{R}} 1_{|x-y| \leq L} |x-y|^{-\frac{1}{2}} W'(dy)$$

- W' and W are independent.

- Remark $\langle X_\eta^2 \rangle$ diverges when $\eta \rightarrow 0$

- Hints :

$$\langle X_\eta^2 \rangle = \frac{1}{2} \int_{|y| \leq L} |y|^{-\frac{1}{2}} dy = \int_0^L |y|^{-\frac{1}{2}} dy$$

$$\approx \int_0^{\eta} y^{-\frac{1}{2}} dy + \int_{\eta}^L \frac{dy}{y} = \ln \frac{L}{\eta} + O(1)$$

- Nomenclature : $\lim_{\eta \rightarrow 0} e^{\gamma X_\eta(x) - \frac{\eta^2}{2} \langle X_\eta^2 \rangle}$ is called a **Multiplicative Chaos** by Kahane.

- As mentioned, $\langle (\Delta u_x)^2 \rangle$ is not affected by intermittency. In particular $\lim_{\gamma \rightarrow 0} \langle (\Delta u_x)^2 \rangle \underset{l \rightarrow 0}{\sim} c \epsilon l^{2H}$
- Proposition: For $\gamma^2 < H$, we have

$$\lim_{\gamma \rightarrow 0} \langle (\Delta u_x)^4 \rangle \text{ finite, and } \underset{l \rightarrow 0}{\sim} c \epsilon l^{4H-4\gamma^2}$$

Motto:

$$\text{Similarly, consider } \Delta u_x(l) = \int \phi_e(y) e^{2X_2(y) - 4\gamma^2 \langle X_2^2 \rangle} w(dy)$$

$$\text{We get, using } \phi_e(y) = \frac{1}{l} \epsilon(l-y) |l-y|^{H-\frac{1}{2}} - \frac{1}{l} \epsilon(y) |y|^{H-\frac{1}{2}}$$

$$\langle (\Delta u_x)^4 \rangle = 3 \int \phi_e^2(y) \phi_e^2(z) \underset{dy dz}{\int} e^{2X_2(y) + 2X_2(z) - 4\gamma^2 \langle X_2^2 \rangle}$$

$$= 3 \int \phi_e^2(y) \phi_e^2(z) e^{4\gamma^2 \langle X_2(y) X_2(z) \rangle} dy dz$$

$$= 3 \int \phi_e^2(y) \phi_e^2(z) \left(\frac{l}{|y-z|^\gamma} \right)^{4\gamma^2} dy dz$$

Rescale the dummy variables y and z by l to exhibit scalings

$$\Rightarrow \langle (\Delta u_x)^4 \rangle \underset{l \rightarrow 0}{\sim} 3 \frac{l^4}{l} (0) \times \text{factor}(H, \gamma^2) \times l^{4H-4\gamma^2}$$

If the factor (H, γ^2) does not blow up, which is the case for $\gamma^2 < H$ (ask Jason Remaneve)

Conclusions :

We have built an intermittent velocity field $\langle u \rangle$ such that, for not too big values of γ ,

$$\lim_{\gamma \rightarrow 0} \langle (\delta e u_\eta)^q \rangle \underset{l \rightarrow 0}{\sim} A q l^{\xi_q}$$

with

$$\xi_q = qH - q(q^2) \frac{\gamma^\ell}{\ell}$$

But too simplistic to reproduce $4/5$ -law ($A_3 = 0$)

For developments on this subject, see :

PEREIRA, GARBAN, CHEVILLARD, JFM (2016)

CHEVILLARD, GARBAN, RHODES, VARGAS, Annales Henri Poincaré (2019)

RENUVE, Phd (2019).